

# Constant curvature conical metrics

Xuwen Zhu

Joint with Rafe Mazzeo and Bin Xu

# Outline

- 1 Uniformization with conical singularities
- 2 Deformation rigidity
- 3 Compactified configuration space

# Constant curvature metrics on Riemann surfaces

- Classical uniformization theorem: for a given Riemann surface, there is a unique (smooth) constant curvature metric

$$\text{(Gauss–Bonnet)} \quad \chi(M) = \frac{1}{2\pi}KA$$

$\chi(M)$  = Euler characteristic ,  $K$  = curvature ,  $A$  = area

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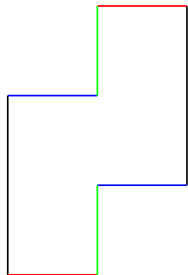
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- Near a cone point with angle  $2\pi\beta$ , in geodesic polar coordinates

$$g = \begin{cases} dr^2 + \beta^2 r^2 d\theta^2 & K = 0 & \text{(flat)} \\ dr^2 + \beta^2 \sin^2 r d\theta^2 & K = 1 & \text{(spherical)} \\ dr^2 + \beta^2 \sinh^2 r d\theta^2 & K = -1 & \text{(hyperbolic)} \end{cases}$$

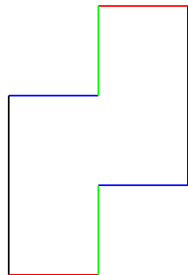
- In conformal coordinates  $z = (\beta r)^{1/\beta} e^{i\theta}$ ,  $g = f(z) |z|^{2(\beta-1)} |dz|^2$

# Some examples of constant curvature conical metrics

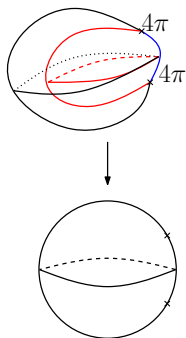


Translation  
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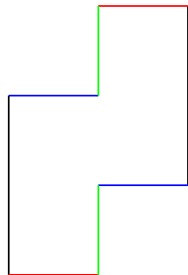


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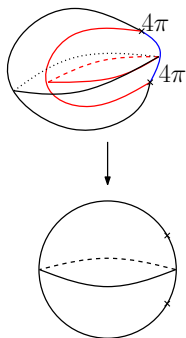


Branched covers  
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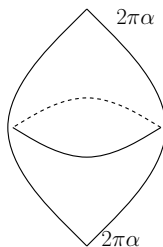
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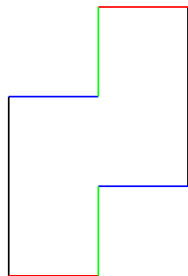
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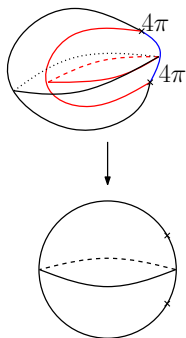
Spherical  
footballs  
( $K = 1$ )



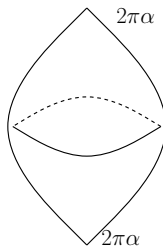
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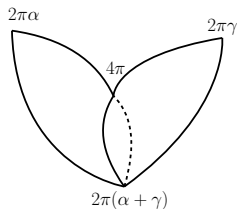
Translation surfaces  
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Branched covers of constant curvature surfaces  
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Spherical footballs  
( $K = 1$ )



“Heart”: footballs glued along geodesics  
( $K = 1$ )

The study of constant curvature conical metrics is related to:

- Magnetic vortices: solitons of gauged sigma-models on a Riemann surface
- Mean Field Equations: models of electro-magnetism
- Toda system: multi-dimensional version
- Higher dimensional analogue: Kähler–Einstein metrics with conical singularities
- Bridge between the (pointed) Riemann moduli spaces: cone angle from 0 to  $2\pi$

This subject can be approached in many ways:

- PDE: singular Liouville equations
- Complex analysis: developing maps and Schwarzian derivatives
- Synthetic geometry: cut-and-glue

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# A singular uniformization problem

Consider the following “conical data”:

- $n$  distinct points  $\mathfrak{p} = (p_1, \dots, p_n)$
- Angle data  $\vec{\beta} = (\beta_1, \dots, \beta_n)$ ,  $\beta_i \in \mathbb{R}^+ \setminus \{1\}$
- Conformal structure  $\mathfrak{c}$  given by the underlying Riemann surface

## Question

Given conical data  $(\mathfrak{p}, \vec{\beta}, \mathfrak{c})$ , does there exist a unique constant curvature conical metric with this data?

# When uniformization holds

Theorem (Heins '62, McOwen '88, Troyanov '91, Luo–Tian '92)

For any compact Riemann surface  $(M, c)$  and conical data  $(p, \vec{\beta})$  with

- $\chi(M, \vec{\beta}) \leq 0$ ; or
- $\chi(M, \vec{\beta}) > 0$ ,  $\vec{\beta} \in T \subset (0, 1)^k$  where  $T$  is the Troyanov region

there is a unique constant curvature conical metric with this data.

Theorem (Mazzeo–Weiss '15)

If  $\vec{\beta} \in (0, 1)^k$ , then there is a well-defined  $(6\gamma - 6 + 3k)$ -dimensional moduli space.

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# Spherical metrics with large cone angles

- The remaining case:  $\chi(M, \vec{\beta}) > 0$ , at least one of the angles greater than  $2\pi$
- Uniformization fails in this case
- **Existence:** constraints on conical data  $(p, \vec{\beta}, c)$   
Mondello–Panov '16, Chen–Lin '17, Chen–Kuo–Lin–Wang '18...
- **Uniqueness:** usually fails  
Chen–Wang–Wu–Xu '14, Eremenko '17,  
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- **Deformation:** obstructions exist [Z '19]
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# Outline of the main result

Our results provide new understanding of the local structure of the moduli space where it is not smoothly parametrized:

## Theorem (Mazzeo–Z '19)

- *The local deformation with respect to  $(c, p, \vec{\beta})$  has rigidity precisely when  $2 \in \text{Spec}(\Delta_g^{\text{Fr}})$ ;*
- *It can be “desingularized” by adding more coordinates via splitting of cone points.*

- Understanding this problem through a nonlinear PDE:

$$\begin{array}{c} \{\text{Constant curvature } K \text{ conical metrics}\} \\ \updownarrow \\ \left\{ \begin{array}{l} \text{Solutions to the Liouville equation} \\ \Delta_{g_0} u - Ke^{2u} + Kg_0 = 0 \end{array} \right\} \end{array}$$

Here  $g_0$  is either a smooth metric (then  $u$  has singularities); or a conical metric with the given conical data (then  $u$  is bounded).

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# Setup

- From now on we study spherical metrics ( $K = 1$ )
- We fix the Riemann surface  $(M, c)$  and do not vary cone angles
- $\mathcal{U}(\vec{\beta})$ : the space of all cone metrics (not necessarily spherical) with cone angles  $\vec{\beta} \in \mathbb{R}^n$
- $\mathbf{p} : \mathcal{U}(\vec{\beta}) \rightarrow M^n$  the positions of the cone points
- $\mathcal{S}(\vec{\beta}) \subset \mathcal{U}(\vec{\beta})$ : the set of **spherical** cone metrics
- In general  $\mathbf{p} : \mathcal{S}(\vec{\beta}) \rightarrow M^n$  is not a local diffeomorphism: we cannot parametrize elements of  $\mathcal{S}(\vec{\beta})$  by cone point positions [Z '19]
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# Deformation and linear obstructions

- Fix  $g_0 \in \mathcal{S}(\vec{\beta})$ . We study local deformations  $g_t : (-\epsilon, \epsilon) \rightarrow \mathcal{S}(\vec{\beta})$  and cone point positions  $p_t = \mathbf{p}(g_t)$ .
- We have  $g_t = e^{2u_t}g_0$ , where  $u_t$  satisfies  $u_0 = 0$  and solves the **singular Liouville equation**

$$\Delta_{g_0} u_t - e^{2u_t} + 1 = 0,$$

Linearized equation:  $(\Delta_{g_0} - 2)v = 0$  where  $v := \partial_t u_t|_{t=0}$

- If  $v \in \ker(\Delta_{g_0}^{\text{Fr}} - 2)$  where  $\Delta_{g_0}^{\text{Fr}}$  is the Friedrichs Laplacian, then  $\partial_t p_t|_{t=0} = 0$ : obstruction to **injectivity of  $\mathbf{p}$** .
- $\partial_t p_t|_{t=0}$  gives the singular terms of  $v$  (those not in the Friedrichs domain). If  $\ker(\Delta_{g_0}^{\text{Fr}} - 2) \neq 0$  then it might be impossible to find a solution with given singular terms: obstruction to **surjectivity of  $\mathbf{p}$** .
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# Is 2 an eigenvalue of $\Delta_g^{\text{Fr}}$ ?

- When  $\vec{\beta} \in (0, 1)^k$ : the only spherical metrics with eigenvalue 2 are footballs (Bochner's technique / integration by parts)
- When at least one  $\beta_i > 1$ : the argument would not work any more
- Examples of metrics with  $2 \in \text{Spec}(\Delta_g^{\text{Fr}})$ : footballs, "heart", branched covers of the standard sphere
- Metrics with reducible monodromy all satisfy  $2 \in \text{Spec}(\Delta_g^{\text{Fr}})$
- These eigenfunctions generate gauge transformations [Xu-Z '19]

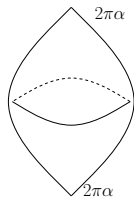
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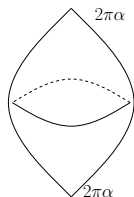
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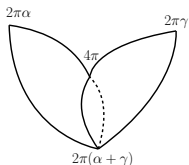


- There is one eigenfunction  $\Delta_g^{\text{Fr}}\phi = 2\phi$
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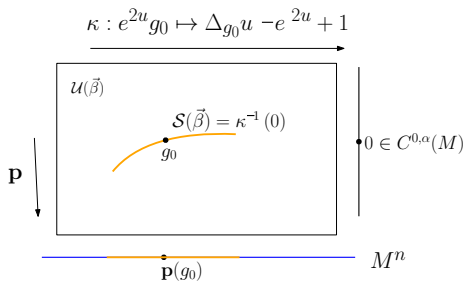


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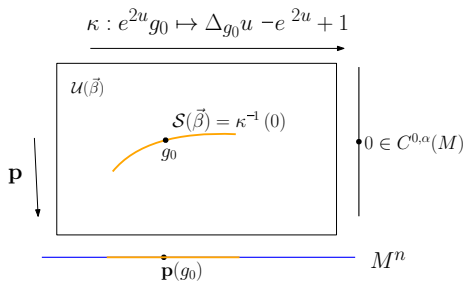
- The eigenfunctions on two footballs glue to a good eigenfunction  $\psi$
- The complex gradient vector field of  $\psi$  again corresponds to conformal dilations
- This generates a family of spherical metrics with the same  $\vec{\beta}$
- **Rigidity**: this family gives all spherical metrics with such  $\vec{\beta}$  [Z '19]

# A schematic picture

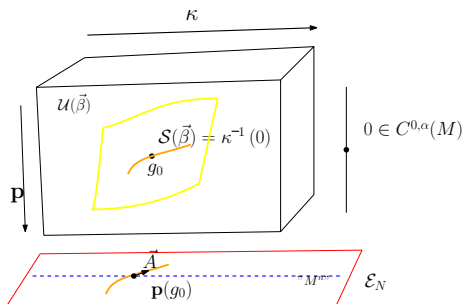


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When  $2 \in \text{Spec}(\Delta_{g_0}^{\text{Fr}})$ , in order to  
 get a surjective map, we need to  
 enlarge the parameter space to  
 include splitting

# A trichotomy theorem

## Theorem (Mazzeo–Z, '19)

*Let  $(M, g_0)$  be a spherical conic metric. Let  $N = \sum_{j=1}^k \max\{[\beta_j], 1\}$ . Let  $\ell$  be the multiplicity of the eigenspace of  $\Delta_{g_0}^{\text{Fr}}$  with eigenvalue 2. There are three cases:  $\ell = 0$ ,  $1 \leq \ell < 2N$ ,  $\ell = 2N$ .*



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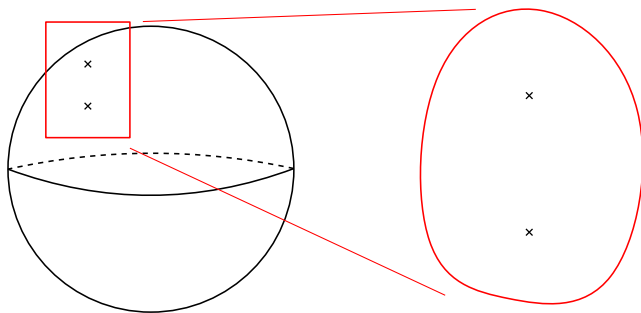
- 1 (Local freeness) If  $\ell = 0$ , then  $g_0 \in \mathcal{S}(\vec{\beta})$  has a smooth neighborhood parametrized by cone positions.
- 2 (Partial rigidity) If  $1 \leq \ell < 2N$ , then there exists a  $2N - \ell$  dimensional  $p$ -submanifold  $X \in \mathcal{E}_N$  that parametrizes the cone position of nearby metrics.
- 3 (Complete rigidity) If  $\ell = 2N$ , then there is no nearby spherical cone metric obtained by moving or splitting the cone points of  $g_0$ .

# Cone points collision

- To set up the nonlinear analysis, one needs to understand the splitting (or merging) of cone points
- We developed an  $\mathcal{C}^\infty$  model that encodes information of such behaviors for **all** constant curvature conical metrics (not only spherical)
- Scale back the distance between two cone points (“blow up”)

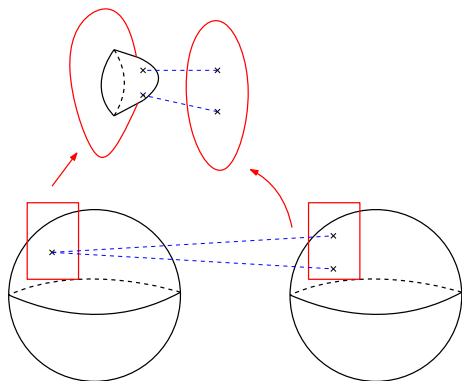
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## When two points collide

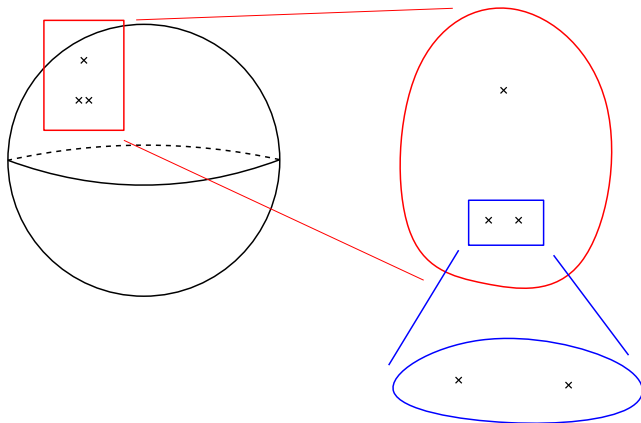
- Scale back the distance between two cone points (“blow up”)
- Half sphere at the collision point, with two cone points over the half sphere:



- Flat metric on the half sphere, and curvature  $K$  metric on the original surface

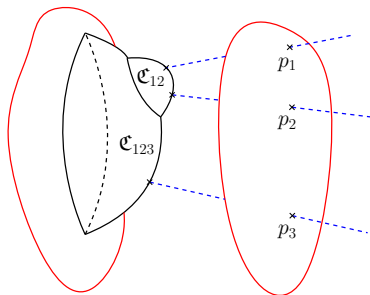
# Iterative structure

- When there are several levels of distance: scale iteratively



# Iterative structure

- “bubble over bubble” structure
- Higher codimensional faces from deeper scaling
- Flat conical metrics on all the new faces



- Iterative singular structures:  
Albin & Leichtnam & Mazzeo & Piazza '09-'19,  
Degeratu–Mazzeo '14, Kottke–Singer '15-'18,  
Albin–Gell–Redman '17, Albin–Dimakis–Melrose '19, .....



# Resolution of the configuration space

This “bubbling” process can be expressed in terms of blow-up of product  $M^k \times M \rightarrow M^k$  ( $k = 2$  in the picture)

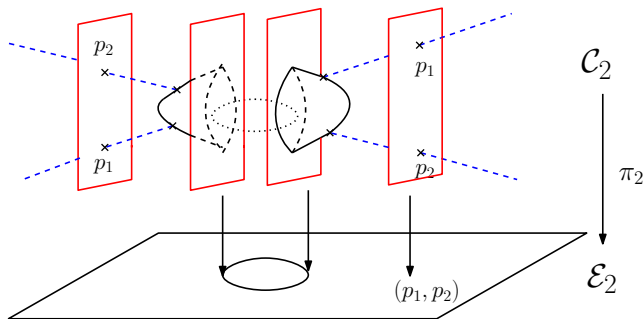


Figure: “Centered” projection of  $\mathcal{C}_2 \rightarrow \mathcal{E}_2$

# Results about fiber metrics

## Theorem (Mazzeo–Z '17)

*For any\* given  $\vec{\beta}$ , the family of constant curvature metrics with conical singularities is polyhomogeneous on this resolved space.*

- \*The metric family can be hyperbolic / flat (with any cone angles), or spherical (with angles less than  $2\pi$ , except footballs)
- Solving the curvature equation uniformly

$$\Delta_{g_0} u - Ke^{2u} + K_{g_0} = 0$$

- The bubbles with flat conical metrics represent the asymptotic properties of merging cones
- We then applied this machinery to understand the big cone angle case [Mazzeo–Z '19]

# Linear constraints given by eigenfunctions

- The splitting creates extra dimensions, which fills up the cokernel of the linearized operator  $\Delta_g^{\text{Fr}} - 2$
- The direction of admissible splitting is determined by the expansion of the eigenfunctions
- Recall  $N = \sum_{j=1}^k \max\{[\beta_j], 1\}$ . An eigenfunction gives a  $2N$ -tuple  $\vec{b}$
- The tangent of splitting directions are given by vectors  $\vec{A}$  that are orthogonal to all such  $\vec{b}$  (linear constraints)
- The bigger dimension of eigenspace, the more constraint on the direction of splitting
- How to get the splitting direction from  $\vec{A}$ : “almost” factorizing polynomial equations

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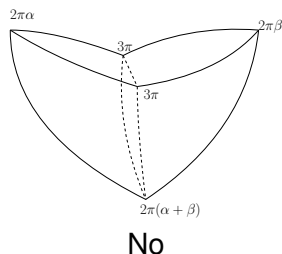
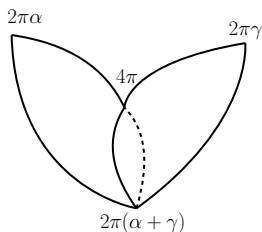
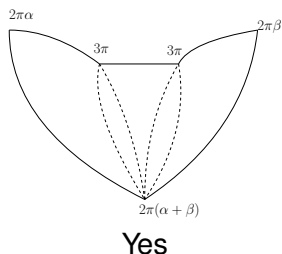
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# An example: open-heart surgery

- We obtain a deformation rigidity for the “heart”
- The cone point with angle  $4\pi$  is split into two separate points
- In the equal splitting case:  $4\pi \rightarrow (3\pi, 3\pi)$
- The spectral data dictates which splitting is possible:



Thank you for your attention!